

Product Information

DYNA 8400 Governor System

General

The DYNA 8400 system will provide an engine governor for speed and power control of piston and gas turbine engines or steam and water turbines.

The actuator is basically a simple, proportional, electric solenoid having a sliding armature whose magnetic force is proportional to input coil current. Balanced between the force of its return spring and the magnetic force, the armature glides on anti-friction bearings, providing a hysteresis-free linear movement. Linear motion is converted to an output shaft rotation by a bell crank.

TYPICAL APPLICATIONS

- Speed governing
- Remote throttle control
- Test stand throttle control
- Generator sets
- Power carts
- Pump sets

SPECIFICATIONS

Actuator

- Operating Voltage 24 VDC, +20%
- Sealed Unit Oil, water and dust tight
- Connection Terminal strip or two-pin connector.
- Actuator Ambient Operating Temperature -65° to + 255°F (55° to +125°C)
- Mechanical Vibration

5 to 500 Hz, Curve F, per Mil-Std.810C, Method 514

Controller

- Operating Voltage 24 VDC, +20%
- Circuit Boards Covered with a heavy conformal coating for moisture and vibration protection
- Connection Terminal strip
- Controller Ambient Operating Temperature -40° to + 180°F (-40° to +85°C)
- Temperature Stability Better than +0.5% over a temperature range of 40° to +167°F (-40° to +75°C)
- Steady State Speed Band +0.25%
- Adjustments Speed, Gain, Integral and Droop
- Mechanical Vibration Withstands the following vibration without failure or degraded performance: 0.06 inch double amplitude at 5 to 18 Hz; 1 G at 18 to 30 Hz; 0.02 inch double amplitude at 30 to 48 Hz; 2.5 G's at 48 to 70 Hz

STANDARD FEATURES

- All-electric
- · All-engine compatibility
- · Mounts in any position
- Engine-mounted (actuator only)
- High reliability due to few moving parts
- Proportional actuator
- No hydraulic or oil line
- No special maintenance
- Spring returns output shaft to minimum position on removal of power or loss of magnetic pickup signal
- Precise Repeatability



AVAILABLE MODELS Actuators: DYNA 8400

Units with terminal strip connections:

• DYNC-14800-000-0-24 Through output shaft making

available CW and CCW output

Units with two-pin MS screw on connector:

• DYNC-14801 -000-0-24 Through output shaft making available CW and CCW output

Controllers: Speed **Input Signal Frequency** DYN1 -10652-000-0-24 250-1200 Hz • DYN1 -10653-000-0-24 1200-2500 Hz • DYN1 -10654-000-0-24 2500-5000 Hz • DYN1 -10656-000-0-24 5000-9500 Hz

Input Signal Frequency

Input Signal Frequency In Hertz =

Engine RPM x Number of Gear Teeth on Flywheel

60 Seconds

Select your controller for the correct input signal frequency range generated by the magnetic pickup at the maximum engine operated (RPM) speed.

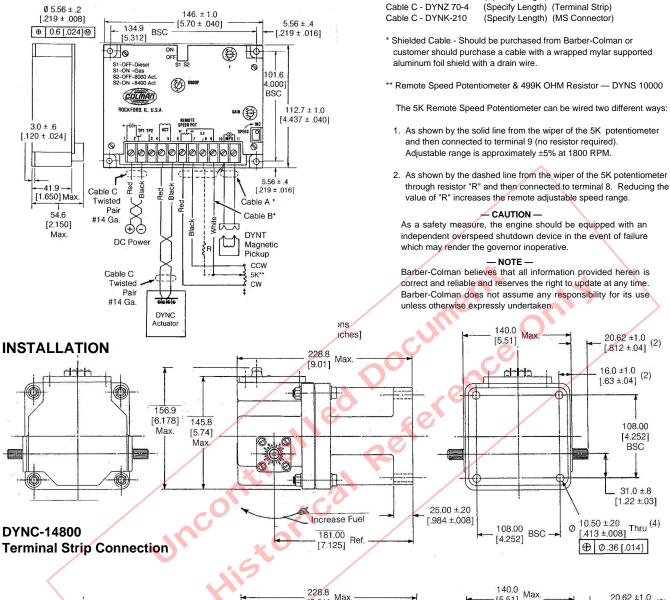
DYNA 8400 Actuator

Mode	Joules	F 4
Work	Joules	5.1
	Foot Pounds	3.75
Torque	Newton-Meters	6.4
	Pound-Foot	4.7
Output	Rotary	45°
Weight	Kilograms	12.2
	Pounds	27
Current @ 24 VDC	Maximum Amperes @ Stall	13
	Nominal Steady State Amperes	4.3
Nominal Response Time for 63% of Stroke (Seconds)		0.104

DYNA 8400 Controller

Output Current	Nominal Quiescent Current	80 mA
@ 24 VDC	Maximum Amperes @ Stall	13 amps
Weight	Kilograms Pounds	0.863 1.9

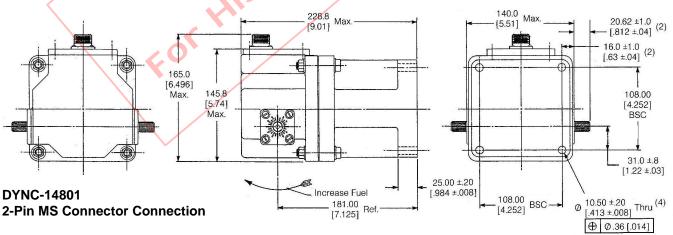
DIMENSIONS — DYNA 8400 CONTROLLER



Cable A - DYNK 44-XX (Specify Length) (90° Connector)

(Specify Length)

Cable B - E26-22



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